



National
Qualifications
2018

X757/77/11

**Physics
Relationships Sheet**

TUESDAY, 8 MAY
9:00 AM – 11:30 AM



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Relationships required for Physics Advanced Higher

$$v = \frac{ds}{dt}$$

$$a = \frac{dv}{dt} = \frac{d^2s}{dt^2}$$

$$v = u + at$$

$$s = ut + \frac{1}{2}at^2$$

$$v^2 = u^2 + 2as$$

$$\omega = \frac{d\theta}{dt}$$

$$\alpha = \frac{d\omega}{dt} = \frac{d^2\theta}{dt^2}$$

$$\omega = \omega_o + \alpha t$$

$$\theta = \omega_o t + \frac{1}{2}\alpha t^2$$

$$\omega^2 = \omega_o^2 + 2\alpha\theta$$

$$s = r\theta$$

$$v = r\omega$$

$$a_t = r\alpha$$

$$a_r = \frac{v^2}{r} = r\omega^2$$

$$F = \frac{mv^2}{r} = mr\omega^2$$

$$T = Fr$$

$$T = I\alpha$$

$$L = mvr = mr^2\omega$$

$$L = I\omega$$

$$E_k = \frac{1}{2}I\omega^2$$

$$F = G\frac{Mm}{r^2}$$

$$V = -\frac{GM}{r}$$

$$v = \sqrt{\frac{2GM}{r}}$$

apparent brightness, $b = \frac{L}{4\pi r^2}$

Power per unit area = σT^4

$$L = 4\pi r^2\sigma T^4$$

$$r_{\text{Schwarzschild}} = \frac{2GM}{c^2}$$

$$E = hf$$

$$\lambda = \frac{h}{p}$$

$$mvr = \frac{nh}{2\pi}$$

$$\Delta x \Delta p_x \geq \frac{h}{4\pi}$$

$$\Delta E \Delta t \geq \frac{h}{4\pi}$$

$$F = qvB$$

$$\omega = 2\pi f$$

$$\omega = \frac{2\pi}{T}$$

$$a = \frac{d^2y}{dt^2} = -\omega^2 y$$

$$y = A \cos \omega t \quad \text{or} \quad y = A \sin \omega t$$

$$v = \pm \omega \sqrt{(A^2 - y^2)}$$

$$E_K = \frac{1}{2} m \omega^2 (A^2 - y^2)$$

$$E_P = \frac{1}{2} m \omega^2 y^2$$

$$y = A \sin 2\pi \left(ft - \frac{x}{\lambda} \right)$$

$$E = kA^2$$

$$\phi = \frac{2\pi x}{\lambda}$$

$$\text{optical path difference} = m\lambda \quad \text{or} \quad \left(m + \frac{1}{2} \right) \lambda$$

where $m = 0, 1, 2, \dots$

$$\Delta x = \frac{\lambda l}{2d}$$

$$d = \frac{\lambda}{4n}$$

$$\Delta x = \frac{\lambda D}{d}$$

$$n = \tan i_p$$

$$F = \frac{Q_1 Q_2}{4\pi \epsilon_0 r^2}$$

$$E = \frac{Q}{4\pi \epsilon_0 r^2}$$

$$V = \frac{Q}{4\pi \epsilon_0 r}$$

$$F = QE$$

$$V = Ed$$

$$F = lB \sin \theta$$

$$B = \frac{\mu_0 I}{2\pi r}$$

$$c = \frac{1}{\sqrt{\epsilon_0 \mu_0}}$$

$$t = RC$$

$$X_C = \frac{V}{I}$$

$$X_C = \frac{1}{2\pi fC}$$

$$\mathcal{E} = -L \frac{dI}{dt}$$

$$E = \frac{1}{2} LI^2$$

$$X_L = \frac{V}{I}$$

$$X_L = 2\pi fL$$

$$\frac{\Delta W}{W} = \sqrt{\left(\frac{\Delta X}{X} \right)^2 + \left(\frac{\Delta Y}{Y} \right)^2 + \left(\frac{\Delta Z}{Z} \right)^2}$$

$$\Delta W = \sqrt{\Delta X^2 + \Delta Y^2 + \Delta Z^2}$$

$$d = \bar{v}t$$

$$s = \bar{v}t$$

$$v = u + at$$

$$s = ut + \frac{1}{2}at^2$$

$$v^2 = u^2 + 2as$$

$$s = \frac{1}{2}(u+v)t$$

$$W = mg$$

$$F = ma$$

$$E_w = Fd$$

$$E_p = mgh$$

$$E_k = \frac{1}{2}mv^2$$

$$P = \frac{E}{t}$$

$$p = mv$$

$$Ft = mv - mu$$

$$F = G \frac{Mm}{r^2}$$

$$t' = \frac{t}{\sqrt{1 - (v/c)^2}}$$

$$l' = l\sqrt{1 - (v/c)^2}$$

$$f_o = f_s \left(\frac{v}{v \pm v_s} \right)$$

$$z = \frac{\lambda_{\text{observed}} - \lambda_{\text{rest}}}{\lambda_{\text{rest}}}$$

$$z = \frac{v}{c}$$

$$v = H_0d$$

$$W = QV$$

$$E = mc^2$$

$$E = hf$$

$$E_k = hf - hf_0$$

$$E_2 - E_1 = hf$$

$$T = \frac{1}{f}$$

$$v = f\lambda$$

$$d \sin \theta = m\lambda$$

$$n = \frac{\sin \theta_1}{\sin \theta_2}$$

$$\frac{\sin \theta_1}{\sin \theta_2} = \frac{\lambda_1}{\lambda_2} = \frac{v_1}{v_2}$$

$$\sin \theta_c = \frac{1}{n}$$

$$I = \frac{k}{d^2}$$

$$I = \frac{P}{A}$$

$$\text{path difference} = m\lambda \quad \text{or} \quad \left(m + \frac{1}{2}\right)\lambda \quad \text{where } m = 0, 1, 2, \dots$$

$$\text{random uncertainty} = \frac{\text{max. value} - \text{min. value}}{\text{number of values}}$$

$$V_{\text{peak}} = \sqrt{2}V_{\text{rms}}$$

$$I_{\text{peak}} = \sqrt{2}I_{\text{rms}}$$

$$Q = It$$

$$V = IR$$

$$P = IV = I^2R = \frac{V^2}{R}$$

$$R_T = R_1 + R_2 + \dots$$

$$\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \dots$$

$$E = V + Ir$$

$$V_1 = \left(\frac{R_1}{R_1 + R_2} \right) V_s$$

$$\frac{V_1}{V_2} = \frac{R_1}{R_2}$$

$$C = \frac{Q}{V}$$

$$E = \frac{1}{2}QV = \frac{1}{2}CV^2 = \frac{1}{2} \frac{Q^2}{C}$$

Additional Relationships

Circle

$$\text{circumference} = 2\pi r$$

$$\text{area} = \pi r^2$$

Sphere

$$\text{area} = 4\pi r^2$$

$$\text{volume} = \frac{4}{3}\pi r^3$$

Trigonometry

$$\sin \theta = \frac{\text{opposite}}{\text{hypotenuse}}$$

$$\cos \theta = \frac{\text{adjacent}}{\text{hypotenuse}}$$

$$\tan \theta = \frac{\text{opposite}}{\text{adjacent}}$$

$$\sin^2 \theta + \cos^2 \theta = 1$$

Moment of inertia

point mass

$$I = mr^2$$

rod about centre

$$I = \frac{1}{12}ml^2$$

rod about end

$$I = \frac{1}{3}ml^2$$

disc about centre

$$I = \frac{1}{2}mr^2$$

sphere about centre

$$I = \frac{2}{5}mr^2$$

Table of standard derivatives

$f(x)$	$f'(x)$
$\sin ax$	$a \cos ax$
$\cos ax$	$-a \sin ax$

Table of standard integrals

$f(x)$	$\int f(x)dx$
$\sin ax$	$-\frac{1}{a} \cos ax + C$
$\cos ax$	$\frac{1}{a} \sin ax + C$

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